

[0116] The value of an azimuthal angle  $\epsilon$  of the above-defined type can be specified e.g. through a biometric inclination angle  $\beta$  (311) defined between a first articular bone 303 of the writing hand index finger 302 and a second articular bone 304 of the writing hand index finger 302, and additionally characterized by the spatial orientation of the axis of rotation (not shown) of the proximal interphalangeal joint 308 of the index finger 312 of the writing hand 302 of the user during writing.

[0117] The axis of rotation of the proximal interphalangeal joint of the index finger is given through the biomechanics of the writing hand, and its orientation relative to the X axis (not shown) is a typical parameter by means of which the individual handwriting can be characterized.

[0118] The biometric inclination angle  $\beta$  (311) can be set, for example by the user, e.g. in default settings of the signal-processing software of the electronic pen 300.

[0119] For the sake of completeness, it should be mentioned that the features, definitions and/or magnitudes which are exemplarily described in the figures can be combined in accordance with the present invention.

[0120] Followed by 3 sheets with 3 figures. The reference numerals identify the following components:

[0121] 100 electronic pen

[0122] 101 first coordinate axis, e.g. X axis

[0123] 102 second coordinate axis, e.g. Y axis

[0124] 103 third coordinate axis, e.g. Z axis

[0125] 104 elevation angle or inclination angle  $\gamma$  of the longitudinal axis of the electronic pen with respect to the writing substrate

[0126] 105 azimuthal angle  $\epsilon$

[0127] 106 projection of the longitudinal axis 107 of the electronic pen 100 onto the writing substrate 108 or line of intersection along which a plane, defined by the longitudinal axis 107 of the pen and a writing substrate perpendicular, intersects the writing substrate plane.

[0128] 107 longitudinal axis of the electronic pen

[0129] 108 writing substrate/writing substrate plane

[0130] 109 writing rod tip

[0131] 110 character written with the electronic pen

[0132] 111 coordinate system X, Y, Z, reference coordinate system

[0133] 200 electronic pen

[0134] 201 first coordinate axis, e.g. X axis

[0135] 202 second coordinate axis, e.g. Y axis

[0136] 203 azimuthal angle  $\epsilon$

[0137] 204 longitudinal axis of the electronic pen

[0138] 205 writing substrate/writing substrate plane

[0139] 206 second character axis or minor axis

[0140] 207 coordinate system X, Y, Z, reference coordinate system

[0141] 208 direction angle  $\eta$  of a preferential direction of writing

[0142] 209 first character axis or major axis

[0143] 300 electronic pen

[0144] 301 longitudinal axis of the electronic pen

[0145] 302 writing hand of a user of an electronic pen 300

[0146] 303 first articular bone of the index finger of the writing hand

[0147] 304 second articular bone of the index finger of the writing hand

[0148] 305 third articular bone of the index finger of the writing hand

[0149] 306 fourth articular bone of the index finger of the writing hand

[0150] 307 first joint (metacarpophalangeal joint) of the index finger of the writing hand

[0151] 308 second joint (proximal interphalangeal joint) of the index finger of the writing hand

[0152] 309 third joint (distal interphalangeal joint) of the index finger of the writing hand

[0153] 310 writing rod tip

[0154] 311 biometric inclination angle  $\beta$

[0155] 312 index finger of the writing hand of a user

[0156] 313 thumb of the writing hand of a user

1. A method of recognizing and evaluating pen positions of an electronic pen (100, 200, 300) with inertial measurement sensors during writing on a two-dimensional writing substrate (108, 205), the method comprising

initially specifying a writing coordinate system with two axes X, Y (101, 102, 201, 202), which are orthogonal to each other on the writing substrate (108, 205) and an axis Z (103) perpendicular to the two-dimensional writing substrate (108, 205), the X axis (101, 201) defining a predominant writing direction, and writing substrate coordinates x, y being defined with respect to said writing coordinate system,

compensating an undesirable drift in a pen position signal of the electronic pen to be output, the compensating comprising:

executing in parallel a coordinate transformation of the azimuthal angle  $\epsilon$  (105, 203) and of the inclination angle  $\gamma$  (104) of the electronic pen (100, 200, 300) into writing substrate coordinates x, y for the values of the azimuthal angle  $\epsilon$  (105, 203) and of the inclination angle  $\gamma$  (104) determined from the inertial measurement sensors as well as for a plurality of additional predetermined values of the azimuthal angle  $\epsilon$  (105, 203) and the inclination angle  $\gamma$  (104), the coordinate transformation comprising

determining the optimum linear combination of the values of the azimuthal angle  $\epsilon$  (105, 203) and of the inclination angle  $\gamma$  (104) at which a minimum deviation of an ascertained acceleration of the electronic pen in the Z direction from a predetermined, expected acceleration in the Z direction is accomplished, and

selecting the determined values of the azimuthal angle  $\epsilon$  (105, 203) and of the inclination angle  $\gamma$  (104), which result in a minimum deviation of an ascertained acceleration of the electronic pen in the Z direction from a predetermined, expected acceleration in the Z direction, for correcting a pen position signal to be output.

2. The method according to claim 1, wherein the azimuthal angle  $\epsilon$  (105, 203) is defined as the angle between the X axis of the coordinate system (111, 207) to be specified and the line of intersection (106) along which a plane, defined by the longitudinal axis of the pen and a writing substrate perpendicular, intersects the writing substrate plane.

3. The method according to claim 1, wherein a value of  $+30^\circ \pm 10^\circ$  is specified as an initial value of the azimuthal angle  $\epsilon$  (105, 203).

4. The method according to claim 1, wherein values of the azimuthal angles  $\epsilon$  (105, 203) and/or of the inclination angles  $\gamma$  (104) are varied in step widths of  $\leq 1^\circ$  or  $\leq 0.1^\circ$  for